NOZZLE UNIT AND METHOD FOR EXCAVATING A HOLE IN AN OBJECT

The invention relates to a nozzle unit for generating an abrasive jet, which nozzle unit comprises:
-   a first nozzle connected to a pressurized carrier fluid supply;
5   -   a mixing chamber in which the first nozzle discharges;
-   a second nozzle connected to the mixing chamber; and
-   an abrasive particle inlet to the mixing chamber.

Such a nozzle unit can be used for excavating a hole
10   into an object.

A nozzle unit in accordance with the above is generally known in the field of abrasive water jet machining. Devices for abrasive water jet machining typically operate at an ambient pressure substantially

15   equal to atmospheric pressure. The water jet, which is virtually free of any solids, is jetted into a mixing chamber at a pressure of well above 1 kbar. A dry abrasive material is kept at atmospheric pressure and due to the jet pump mechanism in the mixing chamber, the

20   abrasive particles are sucked into the mixing chamber through the abrasive particle inlet.

In the field of drilling holes into geological earth formations, an abrasive water jet system including a nozzle unit with a jet pump mechanism can be used for

25   drilling a hole, see for example WO 02/34653. However, the conditions in this field are substantially different from the field of atmospheric abrasive jet machining since the ambient pressure is well above atmospheric

pressure and increases with about 1 bar per 10 meters
depth.

In the case of the atmospheric abrasive water jet
machining systems, air is sucked into the mixing chamber
together with the abrasive particles. This air flow into
the nozzle unit may generate cavitation that can limit
the transfer of kinetic energy from the water jet to the
abrasive material. Consequently, the efficiency of the
nozzle unit, which is based on this kinetic energy
transfer, is limited by the cavitation.

Another important source of cavitation may stem from
turbulence in and around the jet stream. Pressure
fluctuations in the turbulence locally include pressures
below the vapour pressure of the carrier fluid, which
possibly causes vaporization, the creation of gas
bubbles, and cavitation.

There is a desire for a nozzle unit that is able to
impart at an as high as possible efficiency kinetic
energy to abrasive particles at an as low as possible
consumption rate of abrasive particles so that the nozzle
unit can be used within a limited space available in a
typical bore hole in a geological earth formation.

International application WO-A 91/12930 mentions an
efficiency reduction of conventional nozzle units when
applied in increased ambient pressure conditions, and
reports the construction of a nozzle unit that allows for
a relatively easy modification of the mixing chamber
length. This measure corrects the nozzle design for the
increase in jet divergence caused by the gradual decrease
of a cavitation shield around the jet with ambient
pressure.

US patent 4,555,872 describes a nozzle apparatus in
accordance with the preamble for generating an abrasive

fluid jet stream having material cutting capabilities for
objects at atmospheric pressure. A first nozzle is
provided with an orifice plate of sapphire, having a
cone-shaped orifice of which the smallest flow opening

5   has a diameter of approximately 0.5 mm (0.020 inch).
Herewith an extremely high pressure-drop is achievable at
a low flow rate. A second nozzle downstream of the first
nozzle is provided in the form of a tapered flow shaping
cone, of which the smallest flow opening has a diameter

10   of approximately 1.5 mm (0.060 inch).
       It has been found that none of the prior art nozzle
units described above is capable of delivering a
satisfactory abrasive jet stream in a high pressure
surrounding such as is typically encountered when

15   drilling holes into geological earth formations, taking
into consideration special boundary conditions that
apply.
       In accordance with the invention there is provided a
nozzle unit for generating an abrasive jet, which nozzle

20   unit comprises a first nozzle connected to a pressurized
carrier fluid supply, a mixing chamber in which the first
nozzle discharges a second nozzle connected to the mixing
chamber, and an abrasive particle inlet discharging in
the mixing chamber, wherein the proportion of the cross

25   sectional area of the first nozzle opening and the cross
sectional area of the second nozzle opening is greater
than or equal to 0.50 and lower than 1.
       For the purpose of this specification, the cross
sectional area A of a nozzle opening is defined as the

30   cross sectional area of a flow opening in a section of
the nozzle with the highest restriction, because the
pressure drop at a certain flow rate is largely
determined by the cross sectional area of the smallest

flow opening in a nozzle. The "diameter" D of a nozzle
opening is defined as $2\sqrt{(A/\pi)}$, which in the case of a
circular flow restriction corresponds to the width of the
flow opening in the smallest waist.

It has been found that the larger the cross sectional
area of the second nozzle flow opening is compared to
that of the first nozzle, the more abrasive particles
need to be entrained in the flow of the carrier fluid in
order to achieve a substantial amount of kinetic energy
transferred from the jet stream created by the first
nozzle (the "driving jet") to the entrained abrasive
particles. This transfer of kinetic energy is considered
to be the efficiency of the nozzle unit.

If the proportion between the first and second nozzle
cross sectional areas is less than 0.5, a relatively
large amount of abrasive particles is required to fill
the space in the second nozzle causing problems to supply
the abrasive particles, in particular in a down-hole
application where there is not much operational volume
available. It would be possible to allow a higher ratio
of entrained fluid verses abrasive particles to enter
into the mixing chamber via the abrasive particle inlet.
However, this leads to an undesired lowering of
efficiency, because the entrained fluid consumes kinetic
energy out of the driving jet but is non-effective for
hole excavating compared to a similar amount of kinetic
energy vested in the abrasive particles. Thus, the lower
limit of allowable proportion between first and second
nozzle cross sectional areas is 0.5.

On the other hand, the cross sectional area of the
second nozzle should always be larger than the area of
the first nozzle, i.e. a proportion of less than 1, in

order to accommodate at least some entrained abrasives in
additon to the high pressure jet stream.

Unlike the design of the nozzle unit described in
WO-A 91/12930, the nozzle unit according to the invention

5   is optimized to accommodate the supply and relative flow
rates of the carrier fluid, the abrasive particles, and
entrained fluid.

It is believed that for this reason the nozzle unit
according to the invention has been satisfactory operable

10   under high ambient pressure, in particular at an ambient
pressure of higher than 50 bars, or of even higher than
300 bars. The nozzle unit is therefore particularly
suitable for application in excavating subterranean earth
formations at depths exceeding a few hundred meters up to

15   several kilometres.

It is remarked that the said proportion of first and
second nozzle cross sectional areas in the nozzle
apparatus of US patent 4,555,872 is only 0.11.

Preferably the said proportion of cross sectional

20   areas is lower than 0.9, so as to ensure that a
sufficient number of abrasive particles can be entrained
in the flow of carrier fluid.

In a preferred embodiment of the invention the length
in the flow direction of the mixing chamber is such, that

25   taking into account the divergence of the jet from the
first nozzle, the diameter of the jet leaving the mixing
chamber is smaller than the diameter of the second nozzle
opening.

It has been found that this preference can be more

30   easily met when the proportion of cross sectional areas
is lower than 0.60. A submerged jet typically has a
divergence of 8°-9° (see "The theory of turbulent jets" by
G.N. Abramovich, MIT press, Massachussetts (1963)). The

length is defined as the distance between the exit
opening of the first nozzle and the entry opening of the
second nozzle. The entry opening is defined as the first
point, where the smallest cross-section is present.

5   In an embodiment of the invention the length of the
mixing chamber is in the range of 0.8-2.0 times the
diameter of the first nozzle opening. This provides for
an efficient mixing of the abrasive particles with the
jet, while keeping the length of the mixing chamber
10   limited. This has the advantage, that the jet can be
placed under an angle, which is necessary when drilling
holes. When using the nozzle unit according the
invention, the nozzle is rotated, such that a hole with a
substantial circular cross section is generated.

15   In view of this use, it is furthermore preferred that
the length of the second nozzle is in a range of
4-10 times the second nozzle diameter.

       In an embodiment of the invention, the second nozzle
is eccentrically arranged relative to the first nozzle
20   with respect to the flow direction. Preferably the
eccentric displacement of the second nozzle has a
component in the direction of the abrasive particle
inlet. Herewith it is constructionally easier to keep the
smallest dimensions of the abrasives supply opening
25   substantially equal to the diameter of the first nozzle,
while maximizing the proportion of the cross sectional
area of the first nozzle to the second nozzle.

       The eccentric displacement is preferably up to the
situation that part of the first nozzle wall is in line
30   with part of the second nozzle wall. In the case of both
a cylindrical first nozzle and a cylindrical second
nozzle the eccentricity E is then equal to half the
difference between the two nozzle diameters.

It is furthermore preferred that at least part of an inside wall of the first nozzle is aligned with at least part of an inside wall of the second nozzle.

In an embodiment of the invention, the nozzle unit comprises a supply channel connected to the abrasive supply inlet, wherein the supply channel surrounds the mixing chamber by an angle of less than 180°. In this way efficient use can be made of the eccentric secondary nozzle configuration when provided. At the same time, the supply inlet should be sufficiently wide to be able to supply abrasive particles without substantial risk of blockage.

The included angle between the flow direction in the supply channel and an axis along the flow direction in the primary nozzle is preferably as small as possible. This way the supplied abrasive particles get an as large as possible velocity component parallel to the jet stream generated by the primary nozzle. In an embodiment of the invention, the angle is smaller than 60°, preferably smaller than 30°. Due to mechanical constraints, the angle is typically larger than 10°.

The invention further relates to a combination of a nozzle unit according to the invention and a separation device for separating magnetical or magnetizable abrasive particles from a fluid, which separation device comprises a magnet body for attracting the abrasive particles out of a fluid flowing along the separation device, and a support surface at least partially enveloping the magnet body, and means for transporting attracted abrasive particles along the support surface to the abrasive particle inlet of the nozzle unit.

The invention also relates to a method of excavating a hole into an object, comprising the steps of:

-    arranging an abrasive jet excavating tool comprising
a nozzle unit according to the invention into the hole;
-    generating an abrasive jet by supplying a pressurized
carrier fluid to the first nozzle and discharging
abrasive particles into the mixing chamber; and
-    directing the abrasive jet into the object.

    For the purpose of this specification, an object is
understood to include primarily earth formations,
including subterranean earth formations, and also cement,
casing steel, or packer material in a well for the
exploration or production of hydrocarbons. Such types of
objects can in normal operation be located several
kilometres depth under the earth surface, such that the
ambient pressure can exceed 300 bars.

    These and other features of the invention will be
elucidated below by way of example and with reference to
the accompanying drawing, wherein

    Figure 1 schematically shows a perspective view of an
embodiment of the nozzle unit according to the invention;

    Figure 2 schematically shows a cross sectional view
of the nozzle unit according to Figure 1 along line X-X;

    Figure 3 shows a calculated graph setting out nozzle
unit efficiency against ratio of nozzle cross sections;
and

    Figure 4 schematically shows a schematic cross
sectional view of an excavating tool comprising the
nozzle unit according to the invention.

    In Figure 1 a perspective view of a nozzle unit 1
according to the invention is shown. The nozzle unit 1 is
advantageously manufactured out of tungsten carbide based
materials, for instance similar materials as used for
mixing tubes in the field of abrasive water jet
machining.

The nozzle unit 1 has an inlet 2, for supply of a
pressurized carrier fluid to the nozzle unit 1. In
addition, the nozzle unit has an abrasive particle
inlet 4. Abrasive particles can reach the abrasive
5   particle inlet via a supply channel that is connected to
the abrasive supply inlet 4. As can be seen in Figure 1,
the supply channel surrounds the abrasive supply inlet 4
by an angle α. The angle α is preferably more than 90°
and less than 180°, and in the preferred embodiment as
10   shown in Figure 1 it is 140°.

Referring now to Figure 2, the inlet 2 leads to a
first nozzle 3. In the embodiment, the first nozzle 3 has
a circular cross section, having a smallest waist
diameter D_1 corresponding to a flow opening having a
15   first cross sectional flow area of A_1 in the narrowest
flow restriction. The nozzle 3 may have a non-circular
cross section instead, such as an oval cross section.

The first nozzle 3 discharges into a mixing
chamber 5, which mixing chamber has a length along its
20   flow direction of L_1 measured between the exit plane 7 of
the first nozzle 3 and the exit plane 8 of the mixing
chamber 5 similar to the definitions given on page 260 of
"Applied fluid dynamics handbook" by R. D. Blevins, 1992
edition Krieger Publishing Company, Florida. The abrasive
25   particle inlet 4 also discharges into the mixing
chamber 5.

The exit plane 7 of the first nozzle 3 is defined as
the plane perpendicular to the flow direction located
just at the point where as seen in flow direction through
30   the nozzle the flow opening widens. Likewise, the exit
plane 8 of the mixing chamber is defined as the plane
perpendicular to the flow direction located just at the
point where as seen in flow direction through the mixing

chamber the flow opening is at its maximum restriction, and thus coincides with the entrance plane of the second nozzle 6. In a similar way as for the first nozzle, there is also defined an exit plane 9 of the second nozzle 6.

5   A second nozzle 6 is connected to the mixing chamber 5 on a downstream side thereof, a smallest waist diameter D_2 corresponding to a flow opening having a first cross sectional flow area of A_2 in the narrowest flow restriction, and a nozzle length L_2 measured between

10   entrance plane 8 and exit plane 9 Like the first nozzle, the second nozzle 6 may have a non-circular cross section, such as an oval cross section, but in the preferred embodiment of Figure 2 the nozzle 6 is circular having a diameter D_2.

15   The second nozzle 6 is eccentrically placed relative to the first nozzle 3. The amount of eccentricity is indicated in the drawing by E. The eccentricity E in this case equals half of the difference between the two nozzle diameters (D_2-D_1) so that the first and second nozzle

20   inside walls on the side opposite of the abrasive particle inlet 4 are aligned with each other.

In operation, a pressurized carrier fluid is supplied to the nozzle unit 1 through inlet 2 from where it is jetted through the first nozzle 3 into the mixing

25   chamber 5 to from a driving jet steam. Abrasive particles, together with an entrainment fluid, are entrained by the driving jet which includes entering through the abrasive particle inlet 4 into the mixing chamber 5. In the mixing chamber 5 a mix of the driving

30   jet, the entrainment fluid and the abrasive particles is formed. The mix is then transported through the second nozzle 6, from where it leaves the nozzle unit 1 in the

form of an abrasive jet. The abrasive jet can be directed
against an object to be excavated.

When the ratio A_1/A_2 is properly chosen, the velocity
of the carrier fluid through the mixing chamber creates
an effective suction drawing the abrasive particles into
the mixing chamber. The abrasive particles are best fed
into the mixing chamber via the abrasive particle inlet 4
together with an entrained fluid or an entrained liquid.

Figure 3 shows a graphic representation of a
calculation of nozzle unit efficiency based on laws of
conservation of energy, using volumetric flow rates for
respectively the carrier fluid through the first nozzle
(Q_{in}), the entrained total volumetric flow rate of fluid
and abrasive particles flowing into the mixing chamber
via the abrasive particle inlet (Q_{ent}), and the flow rate
exiting the nozzle unit, Q_{out}, which is the sum of Q_{in}
and Q_{ent}. The volumetric flow rate of abrasive particles,
Q_{abr}, is part of Q_{ent}. The entrained mass density is a
function of the density of the carrier fluid (typically
1.2 kg/l), the density of the abrasive particles
(typically 7.4 kg/l for steel shot), and the volumetric
concentration of abrasives in the entrainment flow.

On the horizontal axis is plotted the ratio A_1/A_2
representing ratio of the cross sectional area of the
first nozzle opening and the cross sectional area of the
second nozzle opening and on the vertical axis the
efficiency of the nozzle unit in terms of percentage of
kinetic energy transfer from the jet created by the
primary nozzle to the abrasive particles.

A preferred area W is hatched into the graph. The
area is bound by lines 31, 32, 33, and 34, each of which
have been found to result from a certain limits or

constraints associated with generating an abrasive jet
stream in down-hole conditions for drilling holes into a
geological earth formation.

Of these lines, line 31 represents an efficiency of
5   10%, which sets a preferred lower limit necessary to
obtain a minimum excavating rate that is desired to
maintain an economically viable operation.

Line 32 represents the efficiency versus area ratio
behaviour under the condition that Q_{ent} is half of Q_{in}.
10   The drilling-fluid circulation through the well restricts
Q_{in} to a limited range of values. A relative increase of
Q_{ent} compared to Q_{in} corresponds to a lower area ratio
for any efficiency value, but it is considered
impractical for a down hole tool to supply a high flow
15   rate through the abrasive particle inlet in the spatially
restricted down hole environment. The total flow rate
between the mixing chamber and the hole bottom, Q_{out}, is
the sum of Q_{ent} and Q_{in}, and an increasing Q_{ent} leads to
correspondingly increasing fluid and particle velocities
20   in the annular stream. It is preferred to maintain Q_{out}
not higher than 150% of Q_{in}, thus Q_{ent} should not exceed
50% of Q_{in}.

In addition to that, an increase of Q_{ent} also
requires an increase of Q_{abr} in order to at least
25   maintain the efficiency of the nozzle unit. Otherwise,
energy from the jet created by the first nozzle is
transferred to drilling fluid instead of abrasive
particles. The more solids the drilling assembly has to
supply to the nozzle unit the more complex the system
30   becomes. It is preferred to achieve a high efficiency
with an as small as possible supply of entrained
abrasives, Q_{abr}.

For the same reason it has been found that Q_{abr} is best kept at 10% of Q_{in} at the most. Line 33 represents the efficiency versus area ratio behaviour under the condition that Q_{abr} is kept at a constant ratio of 10% of

5   Q_{in}. Lines 33a to 33d show the efficiency versus A_1/A_2 for Q_{abr} = 8, 6, 4, and 2% of Q_{in}, respectively.

Line 34 shows the efficiency versus area ratio behaviour under the condition that 60% of the total entrained volume (liquid and abrasive particles) Q_{ent} is

10   consumed by the abrasive particles. The packing of particles includes voids, and, therefore, the concentration of abrasive particles in the entrained fluid is less than 100%. A typical value for the maximum concentration is 60%, which is the ratio between the

15   typical steel shot bulk density (4.4 kg/l) and grain density (7.4 kg/l). Lines 34a to 34e correspond to the conditions that Q_{abr} = 50, 40, 30, 20, and 10% of Q_{ent}, respectively. It can be seen that the lower the percentage the lower the efficiency. This is due to the

20   fact that a higher fraction of the energy vested in Q_{in} will be transferred to the fluid component of the entrained volume instead of the abrasive particles.

Generally, the ratio A_1/A_2 of the cross sectional area of the first nozzle opening and the cross sectional

25   area of the second nozzle opening should be in a range of 0.50 to 1.0, preferably in a range of 0.50 to 0.90 to allow for higher efficiencies. Efficiencies of 20% or more are achievable by selecting A_1/A_2, to be in a range of 0.50 to 0.80. Most preferably, the area ratio A_1/A_2 is

30   selected in a range of 0.50 to 0.60, to also maximally facilitate the second nozzle to receive a diverged jet stream.

The length of the mixing chamber best lies in a range of 0.80 to 2.0 times D_1. The length L_2 of the second nozzle best lies in a range of 4 to 10 times D_2.

In the preferred embodiment as shown in Figure 2, the ratio A_1/A_2 is 0.56 (corresponding to $D_1/D_2 = 0.75$). The length L_1 of the mixing chamber is 1.1 times D_1; the length L_2 of the second nozzle 6 is 7 times D_2.

The nozzle works best with a carrier fluid in liquid form, particularly water or a drilling mud. The pressure differential over the fist nozzle 3 is typically between 100 and 700 bars. The high pressure jet diverges by approximately 8 to 9° as it leaves the first nozzle 3. With the relative dimensions of the nozzle unit 1 as given above, the high-pressure jet discharged from the first nozzle 3 into the mixing chamber 5, should completely enter into the second nozzle 6. In particular, by having the abrasive particle inlet 4 on one side of the mixing chamber 5 and the inside walls of the first and second nozzles on the opposing side in alignment with each other, it is achieved that the flow from the first nozzle 3 into the second nozzle 6 is optimized.

Figure 4 shows a schematic cross section of an excavation tool comprising a combination 10 of a nozzle unit 1, which may be the nozzle unit as shown in Figures 1 and 2, and a separation device 12 for magnetically separating abrasive particles from a fluid. Other than the nozzle unit, the separation device 12 and the excavation tool are similar to those disclosed in International publication WO 02/34653, the content of which is herewith incorporated by reference.

For this tool the abrasive particles should comprise or be made of a magnetizable material, such as steel shot. The excavating tool 6 is provided with a

longitudinal drilling fluid passage 11 in fluid
communication with the nozzle unit 1 via inlet 2, for
supplying the pressurized carrier fluid.

The separation device 12 comprises a magnetic
5   body 13, rotatably arranged in a support sleeve 15. The
magnetic body 13 generates a magnetic field for retaining
the abrasive particles on the support sleeve 15. The
inlet 4 for abrasive particles is located at the lower
end of the support sleeve 15.

10   The magnetic body 13 has a central longitudinal
shaft 18 and is rotatable relative to the sleeve 15 about
the central longitudinal shaft 18. Drive means 19 are
provided to drive shaft 18. The magnetic body 13 contains
helical bands of increased magnetic field strength and
15   helical bands of relatively low magnetic field strength.
Preferably, the magnetic body 13 is formed by a stack of
individual smaller magnets such as described in
International application PCT/EP2004/051407 of which
application priority is presently claimed and which is
20   hereby incorporated by reference.

The second nozzle 6 is arranged above an optional
foot part 14, and is inclined relative to the
longitudinal direction of the excavation tool 10 at an
inclination angle of 15-30° relative that direction, but
25   other angles can be used. Preferably the inclination
angle is about 21°, which is optimal for abrasively
eroding the bottom of the bore hole 17 by axially
rotating the complete excavation tool 10 about its
longitudinal direction inside the bore hole 17.

30   Further details on various parts of the abrasive
particle recirculation system and excavating tool can be
found in International application PCT/EP2004/051407,
already mentioned above.

In operation, the excavating tool 10 works as follows. The excavation tool 10 is connected to the lower end of the drill string (not shown) that is inserted into the borehole 17. The pressurized carrier fluid is

5   supplied in the form of a drilling fluid that is pumped by a suitable pump (not shown), the drill string and the fluid passage 11 into the nozzle unit 1. During pumping, the drilling fluid is provided with a small amount of abrasive particles.

10   As explained above, the first nozzle 3 is arranged with a flow restriction, over which a pressure drop is present which drives the acceleration of the drilling fluid.

The drilling fluid flows through the mixing chamber 5

15   into the second nozzle 6, and is jetted against the borehole bottom 20. Simultaneously the excavation tool is rotated about its longitudinal axis. A return stream of drilling fluid and abrasive particles flows from the borehole bottom 20 through the annulus between the

20   borehole 17 and the excavation tool, thereby passing along the support sleeve 15.

Simultaneously with pumping of the stream of drilling fluid, the magnet 13 is rotated about its shaft 18. The magnet 13 induces a magnetic field extending to and

25   beyond the outer surface of the support sleeve 15. As the return stream passes along the support sleeve 15, the abrasive particles in the stream are separated out from the stream by the magnetic forces from the magnet 13 which attract the abrasive particles onto the outer

30   surface of the support sleeve 15.

The stream of drilling fluid, which is now substantially free from abrasive magnetic particles, flows further through the bore hole to the pump at

surface and is re-circulated through the drill string
after removal of the drill cuttings.

The magnetic abrasive particles retained on the
support surface 15 are attracted towards the helical band
5   having the highest magnetic field. Due to rotation of the
magnet 13, and the helical bands of high and low magnetic
field strengths, the abrasive particles are forced to
follow a helically downward movement along the support
sleeve 15.

10   As the particles arrive at the abrasive particle
inlet 4, the stream of drilling fluid flowing from the
first nozzle 3 into the mixing chamber 5 again entrains
the abrasive particles. Thus, the abrasive particles are
again jetted against the borehole bottom 20 and

15   subsequently flow in upward direction through the
borehole 17. The cycle is then repeated continuously.

In order to enhance the downward transport of the
abrasive particles along the support sleeve 15, the
support sleeve 15 may by slightly tapered to that its

20   diameter at its lower end is smaller than at its upper
end. A short tapered section 21 may be provided at the
lower end of magnet 13 whereby the support sleeve 15 is
provided with a corresponding conical taper in a manner
that the inlet 4 for abrasive particles provides fluid

25   communication between the support surface 15 surrounding
the tapered section 21 and the mixing chamber 5.

The conical taper is best based on the same angle as
the above-discussed inclination angle of the second
nozzle 6.

30   The support sleeve 15 as shown in Figure 4 is
provided with a helically extending guide plates 24a and
24b protruding outwardly from the surface of the support
sleeve 15. This guides the abrasive particles on their

way down along the support sleeve 15. The downward
transport velocity of the abrasive particles is increased
if the guide plates run vertically parallel to the
longitudinal axis. Preferably, the drilling fluid
5 passage 11 can be provided in longitudinal contact with
the support sleeve 15 as the guide plate, replacing the
separate guide plates 24a and 24b.

Referring again to Figure 4, a magnetic attractor
body 16 is preferably provided adjacent the mixing
10 chamber on the side of the mixing chamber opposite to the
abrasive particle inlet 4. This causes magnetic field
lines to run from the lower end 21 of the magnet to this
magnetic body. As a result, the magnetic field from the
cylindrical magnet is pulled inside the mixing chamber 5.
15 This achieves that the magnetic abrasive particles can
form chains from the lower end of the support surface 15
towards the magnetic attractor body 16, thereby crossing
the jet that is discharged from the first nozzle 3. The
particles in these chains thereby interact with the
20 stream of drilling fluid passing through the mixing
chamber 5, and thus the entrainment of these particles in
the drilling fluid will be enhanced.·

Suitable magnets can be made from any highly
magnetisable material, including NdFeB, SmCo and
25 AlNiCo-5, or a combination thereof. Preferably the magnet
also has a magnetic energy content of at least 140 kJ/m^3
at room temperature, preferably more than 300 kJ/m^3 at
room temperature such as is the case with NdFeB-based
magnets.
30 The sleeve 15 and the drilling fluid passage 11 are
best made of a non-magnetic material. Super alloys,
including high-strength corrosion resistant non-magnetic
Ni-Cr alloys, in particular a Ni-Cr alloy available under

the name Inconel-718, have been found to be particularly
suitable.

Typical dimensions relating to the excavating tool
are given in the following table.

Part name	Reference number	Size
Outer diameter of foot part	14	73 mm
Axial length of magnet	13	120 mm
Outer diameter of magnet	13	29 mm
Diameter in lower part of support surface	15	34 mm
Diameter in upper part of support surface	15	52 mm

5   The abrasive particles have a specific gravity (in
the case of steel shot or steel grit particles: 7-8 SG),
which is substantially higher than the typical specific
gravity of the drilling fluid (0,8-2.3 SG). This improves
the situation that a relatively small volumetric
10   entrainment rate of abrasive material is sufficient for a
substantial kinetic energy transfer.